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# Fitting autoregressive models by reversible jump Markov chain Monte Carlo

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## **Outline**





#### **[Background](#page-3-0)**

- [ARMA models](#page-3-0)
- [MCMC Bayseian Inference and likelihood of ARMA model](#page-4-0)
- A brief intro to RIMCMC
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<span id="page-2-0"></span>Why fit an autoregressive model?



- Approximate the power spectrum of processes
- AR fitting
- Whitening filter and LPC problem
- Stepping stone to full ARMA fitting and rational approximation of spectra
- **o** Order Selection?



<span id="page-3-0"></span>Autoregressive models of order *p*, *AR*(*p*) have the form

$$
Y_n + a_1 Y_{n-1} + \cdots + a_p Y_{n-p} = \mu + \varepsilon_n \qquad \varepsilon_n \sim N(0, \sigma^2) \quad \text{i.i.d.}
$$

If *Y* = (*Y<sub>n</sub>*, *n* > −∞),  $\varepsilon$  = ( $\varepsilon_n$ , *n* > −∞),  $a$  = (1,  $a_1, a_2, ..., a_n$ ) Then (centering *Y*)

$$
(a\star Y)_n=\varepsilon_n
$$

It can be shown that (letting  $A(z) = 1 + a_1 z^{-1} + a_2 z^{-2} + \cdots + a_p z^{-p}$ )

$$
S_Y(z) = \frac{\sigma^2}{A(z)A^*(z^{-*})} = \frac{\sigma^2}{(1 - z_1 z^{-1})(1 - z_1^* z) \cdots (1 - z_p^{-1})(1 - z_p^* z)}
$$

For *Y* to be stationary it is required that  $z_1, \ldots, z_p \in \mathbb{D}$ 





<span id="page-4-0"></span>Given a model and data

- $\bullet$   $\theta$ , model parameters
- *y*, data or observation

 $\pi(\theta|\mathsf{y}) \propto \pi(\mathsf{y}|\theta)\pi(\theta)$ 

In our case given data  $y$  and parameters  $\theta$ ,

$$
y = (y_n, n = 1, 2, ..., M),
$$
  $\theta = (p, \sigma^2, z_1, ..., z_p) = (p, v, z)$ 

We will write

$$
\pi(p,v,z|y) \propto \pi(y|p,v,z)\pi(v,z|p)\pi(p)
$$

Maximal likelihood use optimization to find the a maximum.



#### Likelihood of AR model



Observe that since  $\varepsilon \sim CN(0, \sigma^2 I_M)$  is Gaussian,  $\tilde{Y} = (Y_n, n = 1, ..., M)$  is also Gaussian. So, let var( $\tilde{Y}$ ) =  $\sigma^2 Q_M$  Then the density of  $\tilde{Y}$  my be written

$$
f_{\tilde{Y}}(y) = (\pi \sigma_{\varepsilon}^2)^{-M} |Q_M|^{-1} \exp\left(\frac{-1}{\sigma_{\varepsilon}^2} y^* Q_M^{-1} y\right)
$$

or rather

$$
\pi(y|p, v, z) = (\pi v)^{-M} |Q_M(z)|^{-1} \exp\left(\frac{-1}{v} y^* [Q_M(z)]^{-1} y\right)
$$

We are mainly concerned with the following ratios

$$
\frac{\pi(y|p, v, z')}{\pi(y|p, v, z)} = \frac{|Q_M(z)|}{|Q_M(z')|} \exp\left(\frac{-1}{v} \left( y^* [Q_M(z')]^{-1} y - y^* [Q_M(z)]^{-1} y \right) \right)
$$

$$
\frac{\pi(y|p, v', z)}{\pi(y|p, v, z)} = \left( \frac{v}{v'} \right)^M \exp\left(\left( \frac{-1}{v'} + \frac{1}{v} \right) y^* [Q_M(z)]^{-1} y \right)
$$

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# <span id="page-6-0"></span>A brief intro to RJMCMC

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A generalization of Metropolis-Hastings,

Recall for (regular) MH a purposed move from *x* to *x* ′ is accepted with probability

$$
\alpha = 1 \wedge \frac{\pi(x')q(x,x')}{\pi(x)q(x',x)}
$$

For RJMCMC we wish to include more general spaces

$$
C = \bigcup_{p=1}^{p_{\text{max}}} C_k \qquad \text{where } C_k = \{k\} \times \mathbb{R}^+ \times \mathbb{R}^k
$$

Dimension matching how to jump from  $C_k$  to  $C_{k'}$  in a way will make sense and allow for detailed balance.

$$
g:C_k\times \Omega_r\to C_{k'}\times \Omega_{r'}
$$

So that

- $k + r = k' + r'$
- *g* is a diffeomorphism





$$
\alpha = 1 \wedge \frac{\pi(p', v', z'|y)}{\pi(p, v, z|y)} \cdot \frac{q(v, z|v', z', p, p')q(p|p')}{q(v', z'|v, z, p, p')q(p'|p)} \left| \frac{\partial(v', z')}{\partial(v', z')}\right|
$$
\n
$$
= 1 \wedge \frac{\pi(y|v', z', p')\pi(v', z'|p')\pi(p')}{\pi(y|v, z, p)\pi(v, z|p)\pi(p)} \cdot \frac{q(v, z|v', z', p, p')q(p|p')}{q(v', z'|v, z, p, p')q(p'|p)} \left| \frac{\partial(v', z')}{\partial(v', z')}\right|
$$
\n
$$
= 1 \wedge \frac{\pi(y|v', z', p')}{\pi(y|v, z, p)} \cdot \frac{\pi(v', z'|p')\pi(p')}{\pi(v, z|p)\pi(p)} \cdot \frac{q(v, z|v', z', p, p')q(p|p')}{q(v', z'|v, z, p, p')q(p'|p)} \left| \frac{\partial(v', z')}{\partial(v', z')}\right|
$$

 $\alpha = 1 \wedge$  (likelihood ratio) × (prior ratio) × (proposal ratio) × (Jacobian)





<span id="page-8-0"></span>The parameters of the AR models will be specified by

- the variance of the white noise process
- the poles of the transfer function

The parameter space we wish to explore is

$$
C = \bigcup_{p=1}^{p_{\text{max}}} C_k \qquad \text{where } C_k = \{k\} \times \mathbb{R}^+ \times \mathbb{D}^k
$$

This many of the modeling choices in the sequel follow those of Green in [**?**]. Let

$$
X=(P,V,Z_1,Z_2,\ldots,Z_P)\in C
$$



Priors



$$
f_P(p) = \frac{\lambda^p e^{-\lambda}}{p!} \left( \sum_{j=0}^{p_{\text{max}}} \frac{\lambda^j e^{-\lambda}}{j!} \right)^{-1}
$$

• For the variance *V* let  $u \sim \text{Unif}([-\hat{\beta}, \hat{\beta}])$  and

$$
V = e^u \qquad \text{so that} \qquad f_V(v) = \frac{1}{2\hat{\beta}v} \mathbf{1}_{[-\hat{\beta}, \hat{\beta}]}(\log(v))
$$

The *p* poles are *independent* and chosen randomly (uniformly) over D,

$$
f_{Z_j}(z_j) = \frac{1}{\pi} \mathbf{1}_{\mathbb{D}}(z_j) \quad \text{for } j = 1, \ldots, p
$$



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#### Moves



There are three move types:

- Change in variance, with probability  $\beta_p$  ( $\rho$  is the number of poles)
- Change in pole position, with probability  $\pi_p$
- $\bullet$  Birth or death of pole, with probabilities  $b_p$ , and  $d_p$ , respectively. More precisely, a move from
	- $\triangleright$  *mathcal* $C_p$  to *mathcal* $C_{p+1}$  occurs with probability  $b_p$
	- $\triangleright$  *mathcal* $C_{p+1}$  to *mathcal* $C_p$  occurs with probability  $d_p$

The probabilities observe the following

• 
$$
\beta_p + \pi_p + b_p + d_p = 1
$$
 for all p

$$
\bullet \, d_0 = \pi_0 = b_{p_{\max}} = 0
$$

• 
$$
b_p = c \min\{1, f_p(p+1)/f_p(p)\}\text{, and}
$$
  
\n $d_p = c \min\{1, f_p(p)/f_p(p+1)\}\text{ for some } c \text{ as large as possible so that } b_p + d_p \le 0.9$ 



## Proposals and acceptance ratios

Change in variance. (Move within C*p*)



The new variance V' will be be so that

 $log(V'/V) \sim Unif([-\hat{\beta}, \hat{\beta}])$ 

meaning  $V' = Ve^u$  where  $u \sim \text{Unif}([-\hat{\beta}, \hat{\beta}])$  and so,

$$
f_{V'|V}(v',v) = \begin{cases} \frac{1}{2\hat{\beta}v}, & v' \in \left[ve^{-\hat{\beta}},ve^{\hat{\beta}}\right] \\ 0, & \text{otherwise} \end{cases}
$$

Acceptance ratio reduces to

 $\alpha = 1 \wedge$  (likelihood ratio)



#### Proposals and acceptance ratios

Change in pole position. (Move within C*p*)

Randomly select  $j = 1, \ldots, p$  (uniformly) and the pole  $Z_j$  will be perturbed by  $\tilde{u} \sim \text{CN}(Z_j, \hat{\pi})$  conditioned on  $Z'_j = Z_j + \tilde{u} \in \mathbb{D}$ . This gives

$$
f_{Z'_j|Z_j}(z',z) \propto \begin{cases} \frac{1}{\pi \hat{\pi}} \exp\left(\frac{-1}{\hat{\pi}}|z'-z|^2\right) [I(z)]^{-1}, & z' \in \mathbb{D} \\ 0, & \text{otherwise} \end{cases}
$$

where  $I(z) = \frac{1}{z}$  $\overline{\pi \hat{\pi}}$ ∫  $\int_{\mathbb{D}} \exp \left( \frac{-1}{\hat{\pi}} \right)$  $\left(\frac{-1}{\hat{\pi}}|z'-z|^2\right)$  *dz'* w.r.t Lebesgue measure on ℂ. Acceptance ratio reduces to

$$
\alpha = 1 \land (likelihood ratio) \times \frac{l(z')}{l(z)}
$$



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• Birth of a pole. Move from  $C_p$  to  $C_{p+1}$  All we do is append a pole drawn from the uniform distribution on the unit disk.

$$
\alpha = 1 \land (likelihood ratio) \times \frac{\pi^p \lambda}{p+1} \frac{d_{p+1}}{b_p}
$$

• Death of a pole. Move from  $C_p$  to  $C_{p+1}$  All we do is delete a pole drawn from the uniform distribution of current poles.

$$
\alpha = 1 \land \text{(likelihood ratio)} \times \frac{p+1}{\pi^p \lambda} \frac{b_p}{d_{p+1}}
$$





- <span id="page-14-0"></span>• low acceptance rate  $\approx$  0.0005 (after N = 50,000 steps)
- Instability  $\alpha \rightarrow -\infty$



<span id="page-15-0"></span>Thank you!

